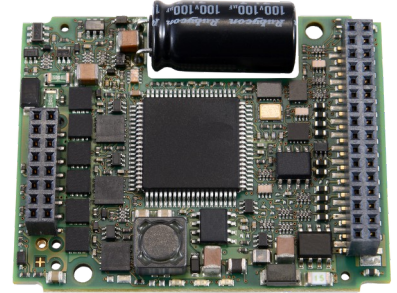


## Servo amplifier

**mcDSA-E61-Modul**

Article number: 1505014



Picture similar

**Technical data**

<b>Absolute maximum rating (destruction limits)</b>	
Power supply voltage $U_p$ no polarity reversal protection	80 V
Continuous Electronic supply voltage $U_e$ no polarity reversal protection	33 V
Short term peak voltage < 1s $U_e$ no polarity reversal protection	37 V
<b>Power</b>	
Electronic supply voltage $U_e$	9..30 V
Electronic current consumption @ $U_e=24V^{*1}$	typ. 25 mA
Power supply voltage $U_p$	9..60 V
Max. output current	15 A
Continuous output current @ $U_p=24V^{*2}$	5 A
Continuous output current @ $U_p=48V^{*2}$	4.3 A
Output voltage	90% $U_p$
PWM frequency	25, 32 <sup>*3</sup> , 50 kHz
<b>Mechanical</b>	
Size LxWxH	52.5 x 41 x 11 mm
Weight	18 g
<b>Environment</b>	
Protection class	IP00
Operating temperature	-40..55 °C
Rel. humidity (non-condensing)	5..90 %
<b>CAN bus</b>	
Protocol	DS301
Device profile	DS402
Max. baudrate	1 Mbit/s
CAN specification	2.0B
Galvanically isolated	no

<b>Auxiliary voltage</b>	
Output voltage	5 V
Max. output current	0.2 A
<b>Encoder</b>	
Type	magnetic sensor
Signals	A, B, Inx channels internally
Resolution	12 bit per motor shaft revolution kHz
Signal type	Magnetic sensor for magnet on the motor shaft
<b>Digital inputs</b>	
Number	4 (Din0..3)
Low voltage	0..5 V
High voltage	8..30 V
<b>Digital outputs</b>	
Number	1 (Dout0)
Continuous output current	1.5 A
Load	resistive, inductive
Output voltage	Electronic supply voltage $U_e$
Signal type	positive switching
<b>Analog inputs</b>	
Number	2 (Ain0..1)
Signal type	0..10 V, 12 Bit, single ended

\*1 power amplifier switched off, 5V output (sensor supply) is free

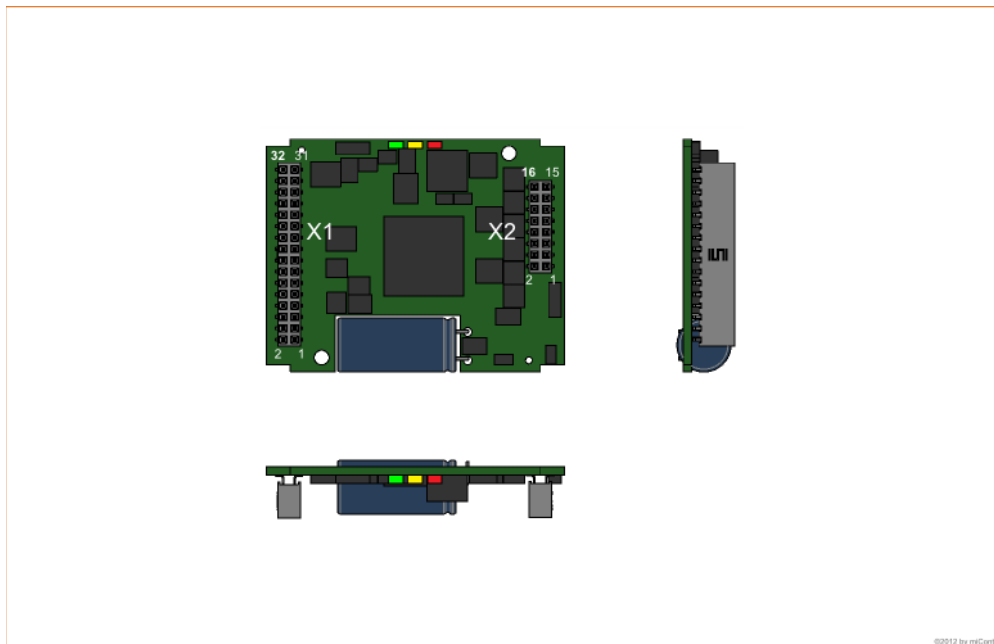
\*2 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C (t > 40 °C derating)  
no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

\*3 default value

Additional technical data are available in mcManual.



Scheme



Terminal assignment

X1	I/O's and CAN	
1	res.	Reserved
2	Id7	Node id bit 7
3	+U5V	5V output voltage (auxiliary voltage)
4	Id6	Node id bit 6
5	res.	Reserved
6	Id5	Node id bit 5
7	res.	Reserved
8	Id4	Node id bit 4
9	res.	Reserved
10	Id3	Node id bit 3
11	res.	Reserved
12	Id2	Node id bit 2
13	res.	Reserved
14	Id1	Node id bit 1
15	CAN Lo	CAN Low
16	Id0	Node id bit 0
17	CAN Hi	CAN High
18	Erw2	mcSPI expansion signal 2
19	Dout0	Digital output 0
20	Erw1	mcSPI expansion signal 1
21	Din2	Digital input 2
22	SpiSCK	mcSPI Clock
23	Din1	Digital input 1
24	SpiMOSI	mcSPI Master Out Slave In
25	Din0	Digital input 0
26	Spi/SS	mcSPI Slave Select
27	Ain0	Analog input 0
28	SpiMISO	mcSPI Master In Slave Out
29	Ain1	Analog input 1
30	Din3	Digital input 3
31	GND	Ground of the auxiliary voltage Notice: don't connect with system GND
32	res.	Reserved

X2	Motor	
1	+Up	Power supply voltage
2	res.	Reserved
3	+Up	Power supply voltage
4	res.	Reserved
5	GND	Ground for power and electronic supply voltage
6	GND	Ground for power and electronic supply voltage
7	Ma	Motor phase A
8	+Ue	Electronic supply voltage
9	Ma	Motor phase A
10	+Ue	Electronic supply voltage
11	Mb	Motor phase B
12	Mb	Motor phase B
13	Mc	Motor phase C
14	res.	Reserved
15	Mc	Motor phase C
16	res.	Reserved