

Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The drive can be configured for a variety of external command signals. Commands can also be configured using the drive's built-in Motion Engine, an internal motion controller used with distributed motion applications. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

Network communication is accomplished using either RS-485/232 or Modbus RTU. This DP Series drive features a single serial interface used for drive commissioning via DriveWare® 7, available for download at www.a-m-c.com.

The DPR Hardware Installation Manual is available for download from www.a-m-c.com. All drive and motor parameters are stored in non-volatile memory.

Power Ra	nge
Peak Current	15 A (10.6 A _{RMS})
Continuous Current	7.5 A (7.5 A _{RMS})
Supply Voltage	100 - 240 VAC





Features

- Four Quadrant Regenerative Operation
- ▲ Space Vector Modulation (SVM) Technology
- ✓ Fully Digital State-of-the-art Design
- Programmable Gain Settings
- Fully Configurable Current, Voltage, Velocity and Position Limits

- PIDF Velocity Loop
- ▲ PID + FF Position Loop
- ▲ 16-bit Analog to Digital Hardware
- On-the-Fly Mode Switching
- On-the-Fly Gain Set Switching

MODES OF OPERATION

- Current
- Position
- Velocity

COMMAND SOURCE

- PWM and Direction
- Encoder Following
- Over the Network
- ±10 V Analog
- SequencingIndexing
- Jogging

FEEDBACK SUPPORTED

- Resolver
- ±10 VDC Position
- Auxiliary Incremental Encoder
- Tachometer (±10 VDC)

INPUTS/OUTPUTS

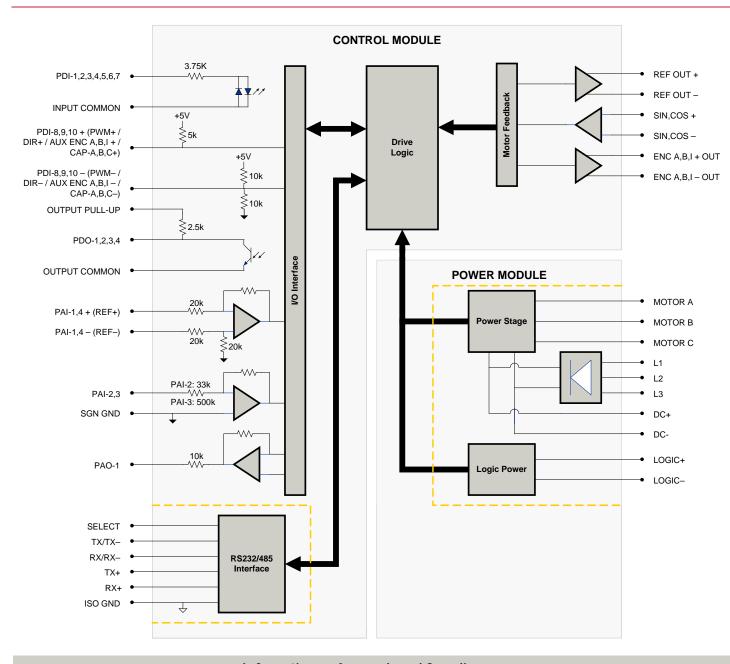
- 3 High Speed Captures
- 4 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 1 Programmable Analog Output (10-bit Resolution)
- 3 Programmable Digital Inputs (Differential)
- 7 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs (Single-Ended)

COMPLIANCES & AGENCY APPROVALS

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS



BLOCK DIAGRAM



Information on Approvals and Compliances



US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.



Compliant with European EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 for Emissions, Class A and EN 61000-6-2:2005 for Immunity, Performance Criteria A). LVD requirements of Directive 2006/95/EC (specifically, EN 60204-1:2004, a Low Voltage Directive to protect users from electrical shock).



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.



SPECIFICATIONS

Power Specifications			
Description	Units	Value	
Rated Voltage	VAC (VDC)	240 (339)	
AC Supply Voltage Range	VAC	100 - 240	
AC Supply Minimum	VAC	90	
AC Supply Maximum	VAC	264	
AC Input Phases ¹	-	3	
AC Supply Frequency	Hz	50 - 60	
DC Supply Voltage Range ²	VDC	127 - 373	
DC Bus Over Voltage Limit	VDC	394	
DC Bus Under Voltage Limit	VDC	55	
Logic Supply Voltage	VDC	20 - 30 (@ 850 mA)	
Maximum Peak Output Current ³	A (Arms)	15 (10.6)	
Maximum Continuous Output Current ⁴	A (Arms)	7.5 (7.5)	
Max. Continuous Output Power @ Rated Voltage ⁵	W	2415	
Max. Continuous Power Dissipation @ Rated Voltage	W	127	
Internal Bus Capacitance	μF	660	
Minimum Load Inductance (Line-To-Line)6	μH	600	
Switching Frequency	kHz	20	
Maximum Output PWM Duty Cycle	%	100	
Low Voltage Supply Outputs		+5 VDC (250 mA)	
Description		ontrol Specifications	
Description Communication Interfaces	Units -	Value RS-485/232 / Modbus RTU	
Communication Interfaces Command Sources	-		
	-	±10 V Analog, Encoder Following, Over the Network, PWM and Direction, Sequencing, Indexing, Jogging	
Feedback Supported	-	±10 VDC Position, Auxiliary Incremental Encoder, Resolver, Tachometer (±10 VDC)	
Commutation Methods	-	Sinusoidal	
Modes of Operation	-	Current, Position, Velocity Classed Lean Vester Single Phase (Prophed Veloc Call Industrial Lead). Three Phase (Prophed)	
Motors Supported Hardware Protection	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless) 40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage	
Programmable Digital Inputs/Outputs (PDIs/PDOs)		10/4	
Programmable Analog Inputs/Outputs (PAIs/PAOs)		4/1	
Primary I/O Logic Level		24 VDC	
Current Loop Sample Time	μs	50	
Velocity Loop Sample Time	μs	100	
Position Loop Sample Time	μs	100	
Resolver Reference/Excitation Signal	Vrms	4 Vrms @ 5 kHz	
Expected Resolver Transformation Ratio	Vrms	0.5	
Feedback Resolution / Emulated Encoder Resolution ⁷	bit	High Res: 14 (16384 counts/resolver cycle), Low Res: 12 (4096 counts/resolver cycle)	
Maximum Motor Speed Per Feedback Resolution	RPM	High Res: 5000, Low Res: 20000	
		chanical Specifications	
Description	Units	Value	
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL	
Size (H x W x D)	mm (in)	177.5 x 139.7 x 55.9 (7 x 5.5 x 2.2)	
Weight	g (oz)	1262 (44.5)	
Heatsink (Base) Temperature Range®	°C (°F)	0 - 65 (32 - 149)	
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)	
Form Factor	-	Panel Mount	
Cooling System	-	Natural Convection	
IP Rating	-	IP10	
+24V LOGIC Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header with threaded flange	
AUX ENCODER Connector	-	15-pin, high-density, male D-sub	
COMM Connector	-	9-pin, female D-sub	
FEEDBACK Connector	-	15-pin, high-density, female D-sub	
I/O Connector	-	26-pin, high-density, female D-sub	
POWER Connector	-	8-port, 7.62 mm spaced, enclosed, friction lock header	

Notes

- Can operate on single-phase VAC if peak/cont. current ratings are reduced by at least 30%.

 Large inrush current may occur upon initial DC supply connection to DC Bus.

 Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.

 Continuous A_{rms} value attainable when RMS Charge-Based Limiting is used.

 P = (DC Rated Voltage) * (Cont. RMS Current) * 0.95.

 Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.

 Higher and lower resolution options are available. Contact Applications Engineering for more information.

 Additional cooling and/or heatsink may be required to achieve rated performance.



PIN FUNCTIONS

	+24V LOGIC - Logic Power Connector		
Pin	Pin Name Description / Notes I/O		
1	LOGIC GND	Logic Supply Ground	GND
2	LOGIC PWR	Logic Supply Input	I

AUX ENCODER - Auxiliary Feedback Connector			
Pin	Name	Description / Notes	1/0
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (PWM+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For	I
5	PDI-8 - (PWM- / AUX ENC A- / CAP-B-)	Single-Ended Signals Leave Negative Terminal Open)	I
6	PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture	I
7	PDI-9 - (DIR- / AUX ENC B- / CAP-C-)	(For Single-Ended Signals Leave Negative Terminal Open)	
8	PDI-10 + (AUX ENC I+ / CAP-A+)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture (For Single-Ended	I
9	PDI-10 - (AUX ENC I- / CAP-A-)	Signals Leave Negative Terminal Open)	I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	0
14	PAI-4 +	Differential December 2011 Annual Institute (40 bit December 2)	I
15	PAI-4 -	Differential Programmable Analog Input (12-bit Resolution)	

	COMM - RS232/RS485 Communication Connector			
Pin	Name	Description / Notes	1/0	
1	SELECT	RS232/485 selection. Pull to ground (CN1-5) for RS485.	I	
2	RS232 TX / RS485 TX-	Transmit Line (RS-232 or RS-485)	0	
3	RS232 RX / RS485 RX-	Receive Line (RS-232 or RS-485)	I	
4	RESERVED	Reserved	-	
5	ISO GND	Isolated Signal Ground	IGND	
6	RS485 TX+	Transmit Line (RS-485)	0	
7	RESERVED	Reserved	-	
8	RS485 RX+	Receive Line (RS-485)	I	
9	RESERVED	Reserved	-	

		FEEDBACK - Feedback Connector	
Pin	Name	Description / Notes	1/0
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	REF OUT +	Resolver Reference/Excitation Output	0
5	REF OUT -	Resolver Reference/Excitation Output	0
6	SIN+	Resolver Sine Input	I
7	SIN-	Resolver Sille Iliput	1
8	COS+	Resolver Cosine Input	I
9	COS-	Resolver Cosine input	1
10	RESERVED	Reserved	-
11	RESERVED	Reserved	-
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	0
14	PAI-3	Programmable Analog Input (12-bit Resolution)	I
15	RESERVED	Reserved	-



		I/O - Signal Connector	
Pin	Name	Description / Notes	1/0
1	PDO-1	Isolated Programmable Digital Output	0
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	0
4	PAI-1 + (REF+)	Differential Drogrammable Angles Input or Deference Cignal Input (46 bit Decelution)	I
5	PAI-1 - (REF-)	Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)	I
6	PAI-2	Programmable Analog Input (12-bit Resolution)	I
7	PAO-1	Programmable Analog Output (10-bit Resolution)	0
8	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	1
9	PDI-5	Isolated Programmable Digital Input	I
10	PDO-3	Isolated Programmable Digital Output	0
11	PDI-1	Isolated Programmable Digital Input	I
12	PDI-2	Isolated Programmable Digital Input	I
13	PDI-3	Isolated Programmable Digital Input	I
14	PDO-4	Isolated Programmable Digital Output	0
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	IGND
16	SGN GND	Signal Ground	SGND
17	PDI-4	Isolated Programmable Digital Input	1
18	PDI-6	Isolated Programmable Digital Input	I
19	PDI-7	Isolated Programmable Digital Input	1
20	ENC A+ OUT	5 1 1 1 5 1 0 1 1 A O 1 1	0
21	ENC A- OUT	Emulated Encoder Channel A Output	0
22	ENC B+ OUT	Family of Family Observed B Outset	0
23	ENC B- OUT	Emulated Encoder Channel B Output	0
24	ENC I+ OUT	F 14 15 1 1 1 0 4 4	0
25	ENC I- OUT	Emulated Encoder Index Output	0
26	SGN GND	Signal Ground	SGND

	POWER - Power Connector			
Pin	Name	Description / Notes	1/0	
1	MOTOR A	Motor Phase A	0	
2	MOTOR B	Motor Phase B	0	
3	MOTOR C	Motor Phase C	0	
4	DC+	Internal DC Rue Valtage (Can Re Head To Connect External Shunt Regulator)	I/O	
5	DC-	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	I/O	
6	L1		I	
7	L2	AC Supply Input (Single or Three Phase)	I	
8	L3		I	



HARDWARE SETTINGS

Switch Functions

Switch	Description	Setting	
Switch		On	Off
1	Bit 0 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
7	Bit 0 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0
8	Bit 1 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0

Additional Details

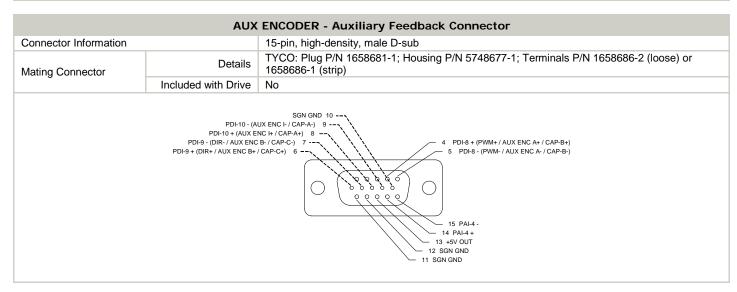
The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

Baud Rate (kbps)	Value For Bit Rate Setting
Load from non-volatile memory	0
9.6	1
38.4	2
115.2	3



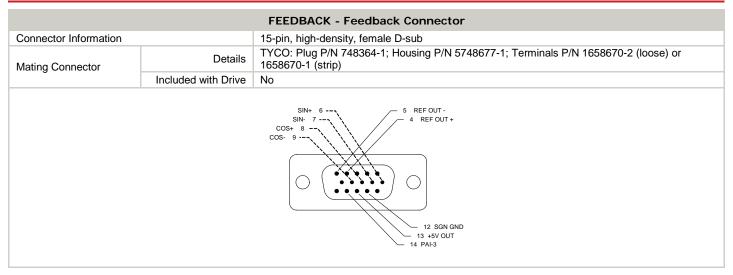
MECHANICAL INFORMATION

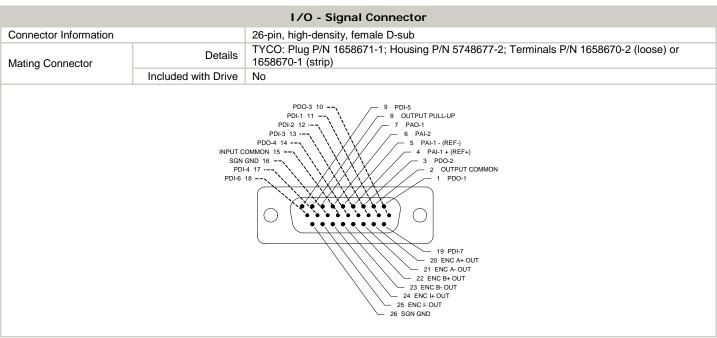
+24V LOGIC - Logic Power Connector		
Connector Information 2-port, 5.08 mm spaced, enclosed, friction lock header with threaded flange		2-port, 5.08 mm spaced, enclosed, friction lock header with threaded flange
Mating Connector	Details	Phoenix Contact: P/N 1777808
Mating Connector	Included with Drive	Yes
		1 LOGIC GND 2 LOGIC PWR

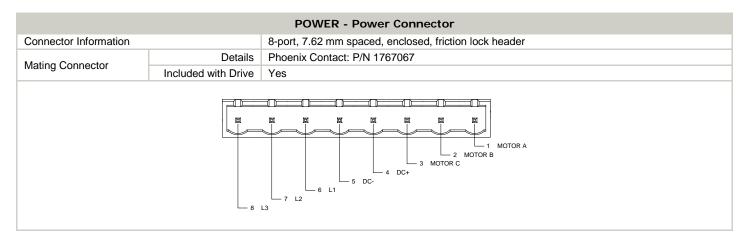


COMM - RS232/RS485 Communication Connector		
Connector Information	Connector Information 9-pin, female D-sub	
Mating Connector Details		TYCO: Plug P/N 205204-4; Housing P/N 5748677-1; Terminals P/N 1658540-5 (loose) or 1658540-4 (strip)
•	Included with Drive	No
		5 ISO GND 3 RS232 RX / RS485 RX- 2 RS232 TX / RS485 TX- 1 SELECT 6 RS485 TX+ 8 RS485 RX+



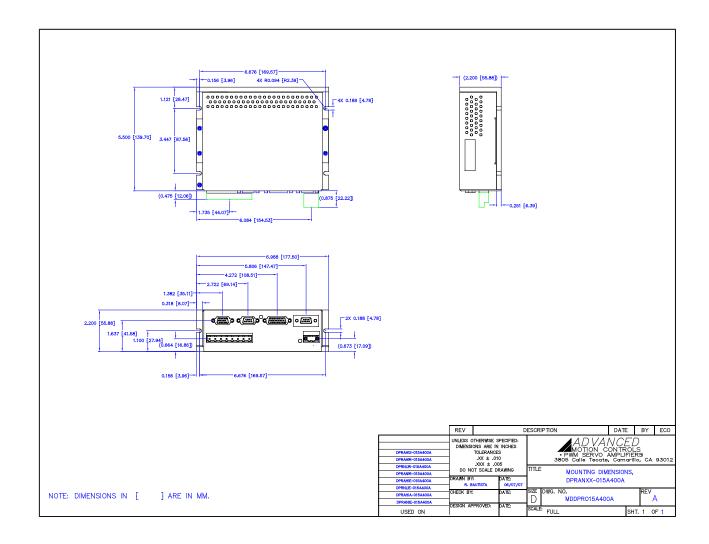






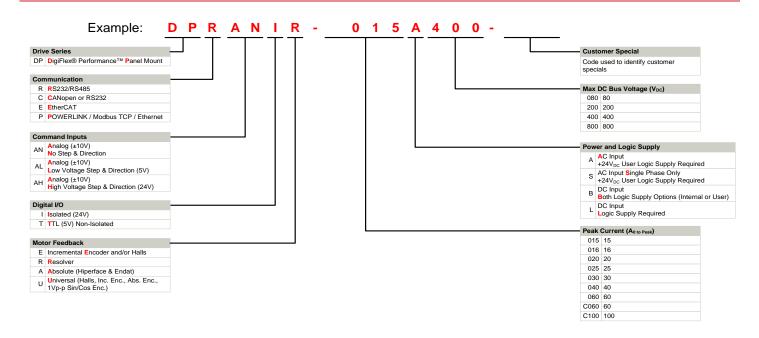


MOUNTING DIMENSIONS





PART NUMBERING INFORMATION



DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

Examples of Customized Products

- Optimized Footprint
- OEM Specified Connectors
- ▲ No Outer Case
- ▲ Increased Current Resolution
- ▲ Increased Temperature Range
- ▲ Custom Control Interface
- ✓ Integrated System I/O

- ✓ Tailored Project File
- ▲ Silkscreen Branding
- Optimized Base Plate
- ✓ Increased Current Limits
- ▲ Increased Voltage Range
- Conformal Coating
- ▲ Multi-Axis Configurations
- ▲ Reduced Profile Size and Weight

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.