

**Description**

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The drive can be configured for a variety of external command signals. Commands can also be configured using the drive's built-in Motion Engine, an internal motion controller used with distributed motion applications. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

Network communication is accomplished using either RS-485/232 or Modbus RTU. This DP Series drive features a single serial interface used for drive commissioning via DriveWare® 7, available for download at [www.a-m-c.com](http://www.a-m-c.com).

The DPR Hardware Installation Manual is available for download from [www.a-m-c.com](http://www.a-m-c.com). All drive and motor parameters are stored in non-volatile memory.

**Power Range**

Peak Current	60 A (42.4 A <sub>RMS</sub> )
Continuous Current	30 A (21.2 A <sub>RMS</sub> )
Supply Voltage	200 - 480 VAC



**Features**

- ▲ Four Quadrant Regenerative Operation
- ▲ Space Vector Modulation (SVM) Technology
- ▲ Fully Digital State-of-the-art Design
- ▲ Programmable Gain Settings
- ▲ Fully Configurable Current, Voltage, Velocity and Position Limits
- ▲ PIDF Velocity Loop
- ▲ PID + FF Position Loop
- ▲ Compact Size, High Power Density
- ▲ 16-bit Analog to Digital Hardware
- ▲ Built-in brake/shunt regulator
- ▲ On-the-Fly Mode Switching
- ▲ On-the-Fly Gain Set Switching

**MODES OF OPERATION**

- Current
- Position
- Velocity
- Hall Velocity

**COMMAND SOURCE**

- PWM and Direction
- Encoder Following
- Over the Network
- ±10 V Analog
- 24V Step and Direction
- Sequencing
- Indexing
- Jogging

**FEEDBACK SUPPORTED**

- Halls
- Incremental Encoder
- ±10 VDC Position
- Auxiliary Incremental Encoder
- Tachometer (±10 VDC)

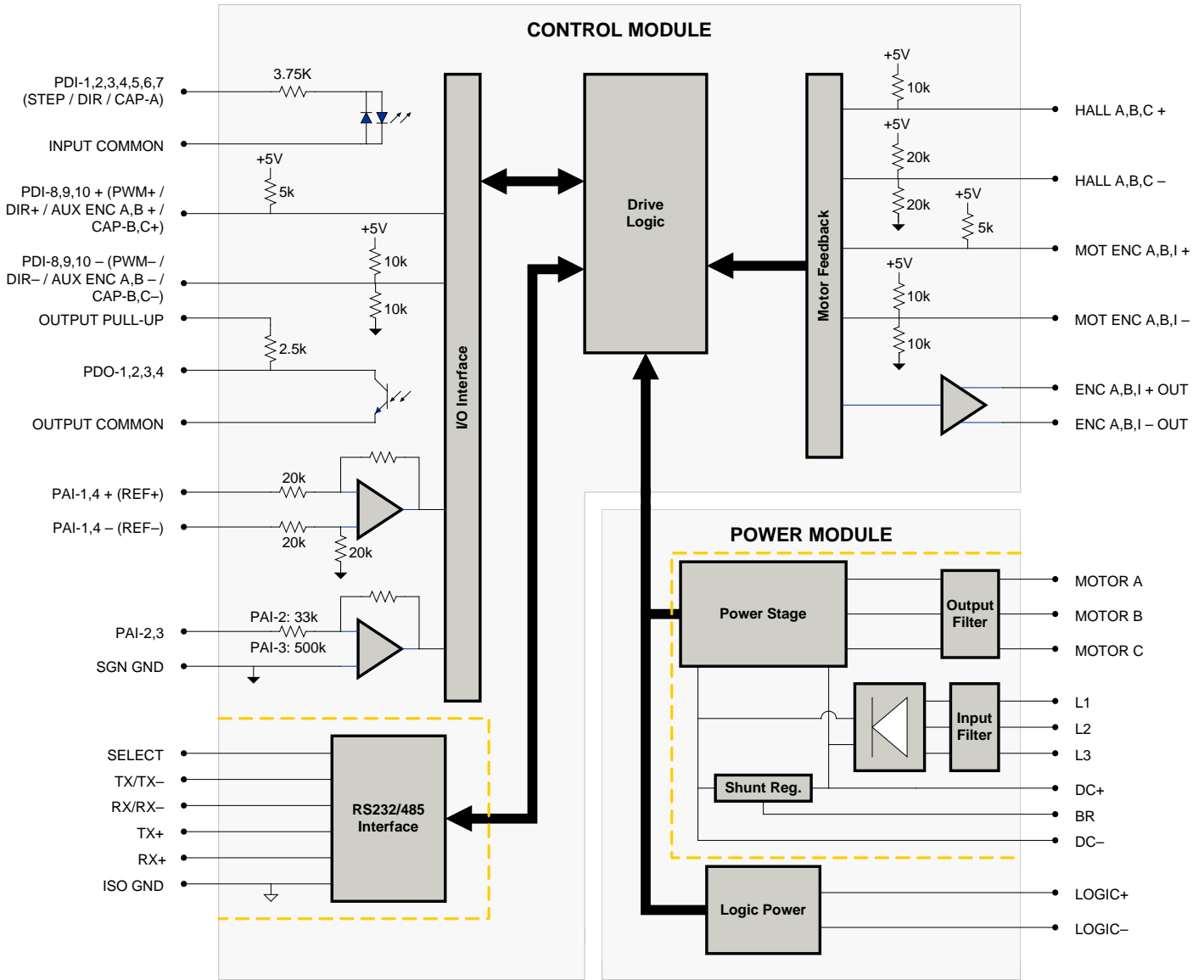
**INPUTS/OUTPUTS**

- 3 High Speed Captures
- 4 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 3 Programmable Digital Inputs (Differential)
- 7 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs (Single-Ended)

**COMPLIANCES & AGENCY APPROVALS**

- CE Class A (LVD)
- CE Class A (EMC)
- RoHS

**BLOCK DIAGRAM**



**Information on Approvals and Compliances**



Compliant with European EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 for Emissions, Class A and EN 61000-6-2:2005 for Immunity, Performance Criteria A). LVD requirements of Directive 2006/95/EC (specifically, EN 60204-1:2004, a Low Voltage Directive to protect users from electrical shock).



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.

**SPECIFICATIONS**

Power Specifications		
Description	Units	Value
Rated Voltage	VAC (VDC)	480 (678)
AC Supply Voltage Range	VAC	200 - 480
AC Supply Minimum	VAC	180
AC Supply Maximum	VAC	528
AC Input Phases	-	3
AC Supply Frequency	Hz	50 - 60
DC Supply Voltage Range <sup>1</sup>	VDC	255 - 747
DC Bus Over Voltage Limit	VDC	850
DC Bus Under Voltage Limit	VDC	230
Logic Supply Voltage	VDC	20 - 30 (@ 850 mA)
Maximum Peak Output Current <sup>2</sup>	A (Arms)	60 (42.4)
Maximum Continuous Output Current	A (Arms)	30 (21.2)
Max. Continuous Output Power @ Rated Voltage <sup>3</sup>	W	13680
Max. Continuous Power Dissipation @ Rated Voltage	W	720
Internal Bus Capacitance	µF	330
External Shunt Resistor Minimum Resistance <sup>4</sup>	Ω	40
Minimum Load Inductance (Line-To-Line) <sup>5</sup>	µH	3000
Switching Frequency	kHz	10
Maximum Output PWM Duty Cycle	%	100
Low Voltage Supply Outputs	-	+5 VDC (250 mA)
Control Specifications		
Description	Units	Value
Communication Interfaces	-	RS-485/232 / Modbus RTU
Command Sources	-	±10 V Analog, 24V Step and Direction, Encoder Following, Over the Network, PWM and Direction, Sequencing, Indexing, Jogging
Feedback Supported	-	±10 VDC Position, Auxiliary Incremental Encoder, Halls, Incremental Encoder, Tachometer (±10 VDC)
Commutation Methods	-	Sinusoidal, Trapezoidal
Modes of Operation	-	Current, Hall Velocity, Position, Velocity
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	10/4
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	4/0
Primary I/O Logic Level	-	24 VDC
Current Loop Sample Time	µs	100
Velocity Loop Sample Time	µs	200
Position Loop Sample Time	µs	200
Maximum Encoder Frequency	MHz	20 (5 pre-quadrature)
Internal Shunt Regulator	-	Yes
Internal Shunt Resistor	-	No
Mechanical Specifications		
Description	Units	Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), RoHS
Size (H x W x D)	mm (in)	300.5 x 232.1 x 139.3 (11.8 x 9.1 x 5.5)
Weight	g (oz)	6165 (217.5)
Heatsink (Base) Temperature Range <sup>6</sup>	°C (°F)	0 - 75 (32 - 167)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Form Factor	-	Panel Mount
Cooling System	-	Natural Convection
IP Rating	-	IP10
+24V LOGIC Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header
AUX ENCODER Connector	-	15-pin, high-density, male D-sub
COMM Connector	-	9-pin, female D-sub
DC BUS Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header
FEEDBACK Connector	-	15-pin, high-density, female D-sub
I/O Connector	-	26-pin, high-density, female D-sub
MOTOR POWER Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header
POWER Connector	-	3-port, 7.62 mm spaced, enclosed, friction lock header

**Notes**

- DC supply operation through the L1, L2, or L3 terminals will reduce peak/cont. current ratings by 30%. See installation manual for details.
- Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
- $P = (\text{DC Rated Voltage}) * (\text{Cont. RMS Current}) * 0.95$ .
- ADVANCED Motion Controls recommends using an external fuse in series with the shunt resistor. A 3 amp motor delay fuse is typical.
- Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
- Additional cooling and/or heatsink may be required to achieve rated performance.

**PIN FUNCTIONS**

<b>+24V LOGIC - Logic Power Connector</b>			
Pin	Name	Description / Notes	I/O
1	LOGIC PWR	Logic Supply Input	I
2	LOGIC GND	Logic Supply Ground	GND

<b>AUX ENCODER - Auxiliary Feedback Connector</b>			
Pin	Name	Description / Notes	I/O
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (PWM+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
5	PDI-8 - (PWM- / AUX ENC A- / CAP-B-)		I
6	PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
7	PDI-9 - (DIR- / AUX ENC B- / CAP-C-)		I
8	PDI-10 +	Programmable Digital Input (For Single-Ended Signals Leave Negative Terminal Open)	I
9	PDI-10 -		I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-4 +	Differential Programmable Analog Input (12-bit Resolution)	I
15	PAI-4 -		I

<b>COMM - RS232/RS485 Communication Connector</b>			
Pin	Name	Description / Notes	I/O
1	SELECT	RS232/485 selection. Pull to ground (CN1-5) for RS485.	I
2	RS232 TX / RS485 TX-	Transmit Line (RS-232 or RS-485)	O
3	RS232 RX / RS485 RX-	Receive Line (RS-232 or RS-485)	I
4	RESERVED	Reserved	-
5	ISO GND	Isolated Signal Ground	IGND
6	RS485 TX+	Transmit Line (RS-485)	O
7	RESERVED	Reserved	-
8	RS485 RX+	Receive Line (RS-485)	I
9	RESERVED	Reserved	-

<b>DC BUS - Power Connector</b>			
Pin	Name	Description / Notes	I/O
1	DC-	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	I/O
2	BR	External Brake Resistor Connection	-
3	DC+	Brake Resistor DC+. Connection for brake resistor.	O
4	DC+	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	I/O

<b>FEEDBACK - Feedback Connector</b>			
Pin	Name	Description / Notes	I/O
1	HALL A+	Commutation Sensor Inputs	I
2	HALL B+		I
3	HALL C+		I
4	MOT ENC A+	Differential Encoder A Channel Input (For Single Ended Signals Use Only The Positive Input)	I
5	MOT ENC A-		I
6	MOT ENC B+	Differential Encoder B Channel Input (For Single Ended Signals Use Only The Positive Input)	I
7	MOT ENC B-		I
8	MOT ENC I+	Differential Encoder Index Input (For Single Ended Signals Use Only The Positive Input)	I
9	MOT ENC I-		I
10	HALL A-	Commutation Sensor Input (For Differential Signals Only)	I
11	HALL B-	Commutation Sensor Input (For Differential Signals Only)	I
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-3	Programmable Analog Input (12-bit Resolution)	I
15	HALL C-	Commutation Sensor Input (For Differential Signals Only)	I

I/O - Signal Connector			
Pin	Name	Description / Notes	I/O
1	PDO-1	Isolated Programmable Digital Output	O
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	O
4	PAI-1 + (REF+)	Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)	I
5	PAI-1 - (REF-)		I
6	PAI-2	Programmable Analog Input (12-bit Resolution)	I
7	SGN GND	Signal Ground	SGND
8	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
9	PDI-5	Isolated Programmable Digital Input	I
10	PDO-3	Isolated Programmable Digital Output	O
11	PDI-1	Isolated Programmable Digital Input	I
12	PDI-2	Isolated Programmable Digital Input	I
13	PDI-3	Isolated Programmable Digital Input	I
14	PDO-4	Isolated Programmable Digital Output	O
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	IGND
16	SGN GND	Signal Ground	SGND
17	PDI-4 (STEP)	Isolated Programmable Digital Input or Step	I
18	PDI-6 (DIR)	Isolated Programmable Digital Input or Direction	I
19	PDI-7 (CAP-A)	Isolated Programmable Digital Input or High Speed Capture	I
20	ENC A+ OUT	Buffered Encoder Channel A Output	O
21	ENC A- OUT		O
22	ENC B+ OUT	Buffered Encoder Channel B Output	O
23	ENC B- OUT		O
24	ENC I+ OUT	Buffered Encoder Index Output	O
25	ENC I- OUT		O
26	SGN GND	Signal Ground	SGND

MOTOR POWER - Power Connector			
Pin	Name	Description / Notes	I/O
1	SHIELD	Motor cable shield. Internally connected to protective earth ground.	-
2	MOTOR C	Motor Phase C	O
3	MOTOR B	Motor Phase B	O
4	MOTOR A	Motor Phase A	O

POWER - Power Connector			
Pin	Name	Description / Notes	I/O
1	L3	AC Supply Input (Three Phase)	I
2	L2		I
3	L1		I

**HARDWARE SETTINGS**
**Switch Functions**

Switch	Description	Setting	
		On	Off
1	Bit 0 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
7	Bit 0 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0
8	Bit 1 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0

*Additional Details*

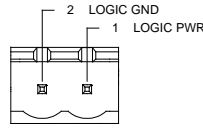
The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

Baud Rate (kbps)	Value For Bit Rate Setting
Load from non-volatile memory	0
9.6	1
38.4	2
115.2	3

**MECHANICAL INFORMATION**

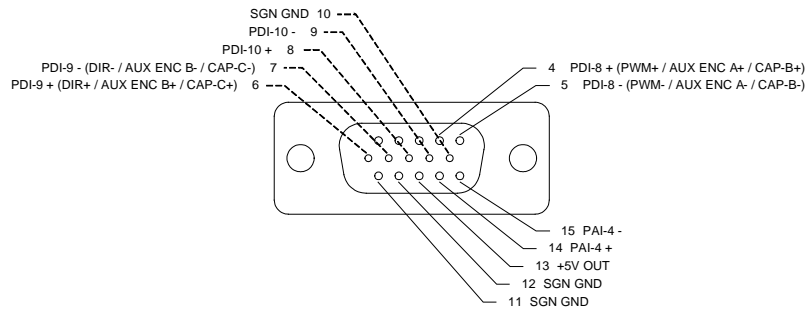
**+24V LOGIC - Logic Power Connector**

Connector Information	2-port, 5.08 mm spaced, enclosed, friction lock header	
Mating Connector	Details	Phoenix Contact: P/N 1757019
	Included with Drive	Yes



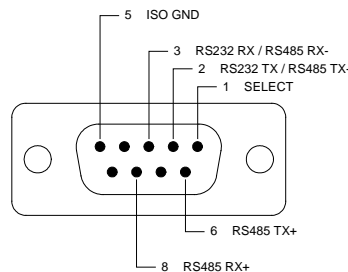
**AUX ENCODER - Auxiliary Feedback Connector**

Connector Information	15-pin, high-density, male D-sub	
Mating Connector	Details	TYCO: Plug P/N 1658681-1; Housing P/N 5748677-1; Terminals P/N 1658686-2 (loose) or 1658686-1 (strip)
	Included with Drive	No



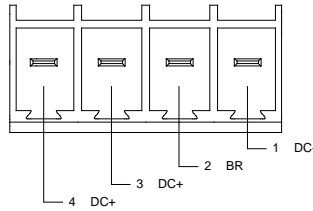
**COMM - RS232/RS485 Communication Connector**

Connector Information	9-pin, female D-sub	
Mating Connector	Details	TYCO: Plug P/N 205204-4; Housing P/N 5748677-1; Terminals P/N 1658540-5 (loose) or 1658540-4 (strip)
	Included with Drive	No



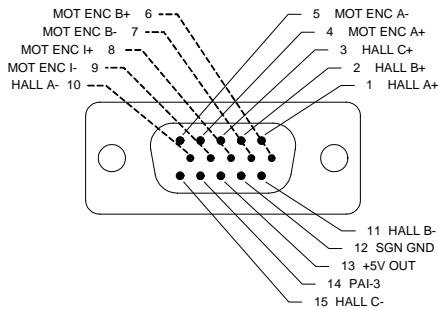
**DC BUS - Power Connector**

Connector Information		4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1804920
	Included with Drive	Yes



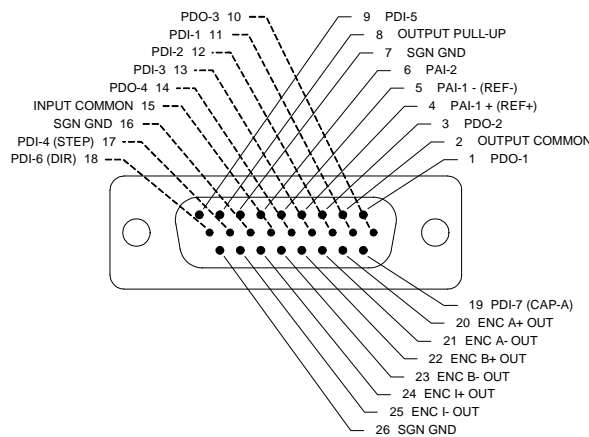
**FEEDBACK - Feedback Connector**

Connector Information		15-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-1; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



**I/O - Signal Connector**

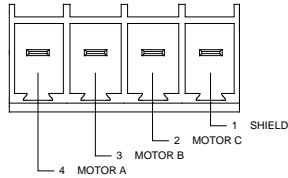
Connector Information		26-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 1658671-1; Housing P/N 5748677-2; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No





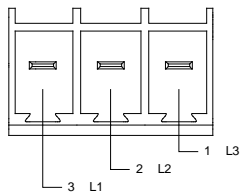
**MOTOR POWER - Power Connector**

Connector Information		4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1804920
	Included with Drive	Yes

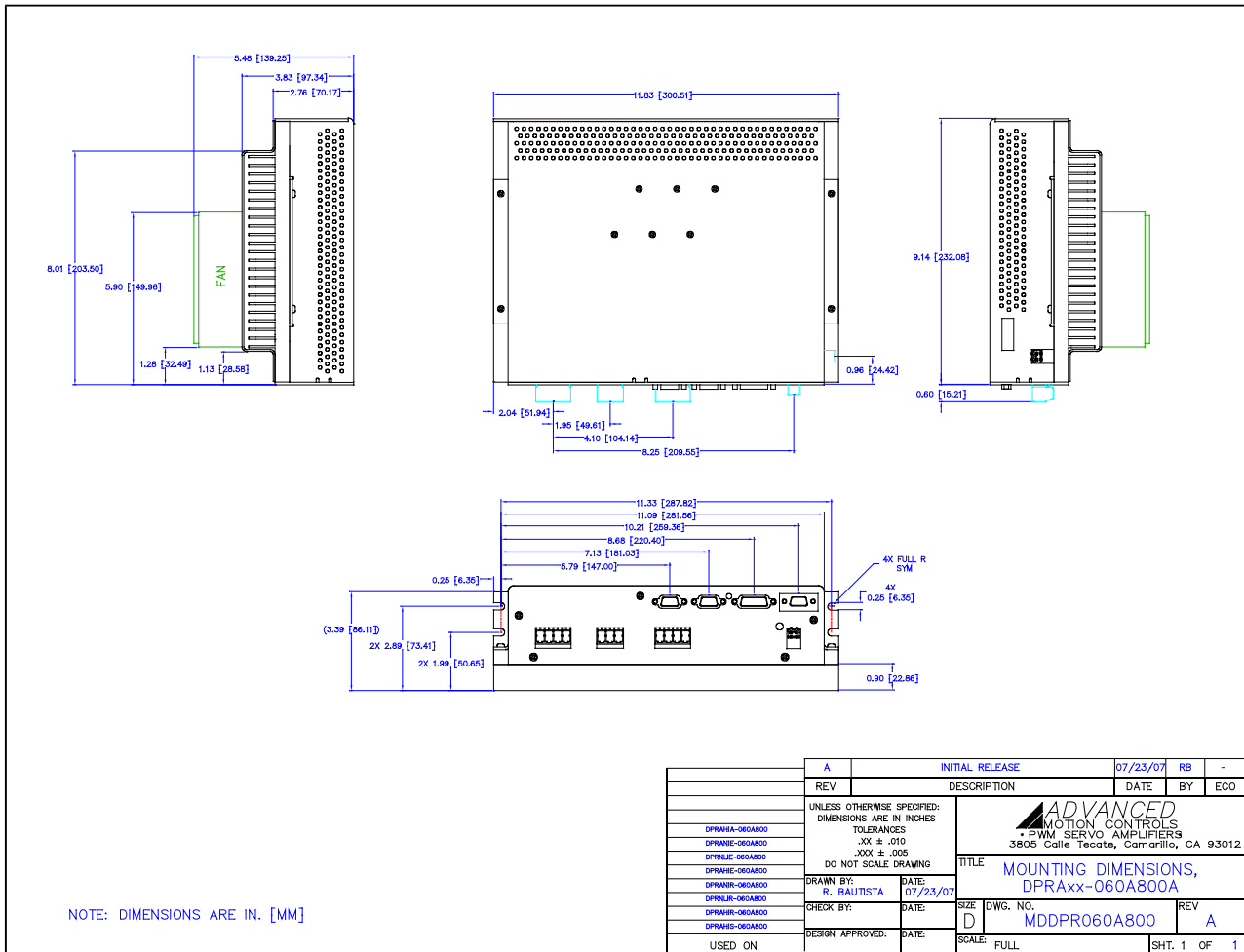


**POWER - Power Connector**

Connector Information		3-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1804917
	Included with Drive	Yes



**MOUNTING DIMENSIONS**



**PART NUMBERING INFORMATION**

Example: **D P R A H I E - 0 6 0 A 8 0 0 -**

<b>Drive Series</b>
DP DigiFlex® Performance™ Panel Mount

<b>Communication</b>
R RS232/RS485
C CANopen or RS232
E EtherCAT
P POWERLINK / Modbus TCP / Ethernet

<b>Command Inputs</b>
AN Analog (±10V) No Step & Direction
AL Analog (±10V) Low Voltage Step & Direction (5V)
AH Analog (±10V) High Voltage Step & Direction (24V)

<b>Digital I/O</b>
I Isolated (24V)
T TTL (5V) Non-Isolated

<b>Motor Feedback</b>
E Incremental Encoder and/or Halls
R Resolver
A Absolute Encoder
U Universal (Halls, Inc. Enc., Abs. Enc., 1Vp-p Sin/Cos Enc.)

<b>Customer Special</b>
Code used to identify customer specials

<b>Max DC Bus Voltage (V<sub>DC</sub>)</b>
080 80
200 200
400 400
800 800

<b>Power and Logic Supply</b>
A AC Input +24V <sub>DC</sub> User Logic Supply Required
S AC Input Single Phase Only +24V <sub>DC</sub> User Logic Supply Required
B DC Input Both Logic Supply Options (Internal or User)
L DC Input Logic Supply Required

<b>Peak Current (A<sub>0</sub> to Peak)</b>
015 15
016 16
020 20
025 25
030 30
040 40
060 60
C060 60
C100 100

DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

**Examples of Customized Products**

- ▲ Optimized Footprint
- ▲ Private Label Software
- ▲ OEM Specified Connectors
- ▲ No Outer Case
- ▲ Increased Current Resolution
- ▲ Increased Temperature Range
- ▲ Custom Control Interface
- ▲ Integrated System I/O
- ▲ Tailored Project File
- ▲ Silkscreen Branding
- ▲ Optimized Base Plate
- ▲ Increased Current Limits
- ▲ Increased Voltage Range
- ▲ Conformal Coating
- ▲ Multi-Axis Configurations
- ▲ Reduced Profile Size and Weight

**Available Accessories**

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit [www.a-m-c.com](http://www.a-m-c.com) to see which accessories will assist with your application design and implementation.



➔  
**To Motor**

All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.