

#### Description

The AZB25A20 PWM servo drive is designed to drive brushless and brushed DC motors at a high switching frequency. To increase system reliability and to reduce cabling costs, the drive is designed for direct integration into your PCB. The AZB25A20 is fully protected against over-voltage, under-voltage, over-current, over-heating and short-circuits. A single digital output indicates operating status. The drive interfaces with digital controllers that have analog ±10V output. This servo drive requires only a single unregulated isolated DC power supply, and is fully RoHS (Reduction of Hazardous Substances) compliant.

See Part Numbering Information on last page of datasheet for additional ordering options.

Power Range	
Peak Current	25 A
Continuous Current	12.5 A
Supply Voltage	40 - 175 VDC



#### **Features**

- ▲ High Power Density
- ▲ Compact Size
- Direct Board-to-Board Integration
- Lightweight
- → High Switching Frequency
- ▲ Four Quadrant Regenerative Operation

- → High Performance Thermal Dissipation
- Differential Input Command
- Current Monitor Output
- Digital Fault Output Monitor
- Wide Supply Voltage Range

## HARDWARE PROTECTION

- Over-Voltage
- Under-Voltage
- Over-Current
- Over-Temperature
- Short-circuit (phase-phase)
- Short-circuit (phase-ground)

# INPUTS/OUTPUTS

- Digital Fault Output
- Digital Inhibit Input
- Analog Current Monitor
- Analog Command Input
- Analog Current Reference

#### **FEEDBACK SUPPORTED**

Hall Sensors

#### MODES OF OPERATION

Current

## COMMUTATION

Trapezoidal

# MOTORS SUPPORTED

- Three Phase (Brushless)
- Single Phase (Brushed, Voice Coil, Inductive Load)

## **COMMAND SOURCE**

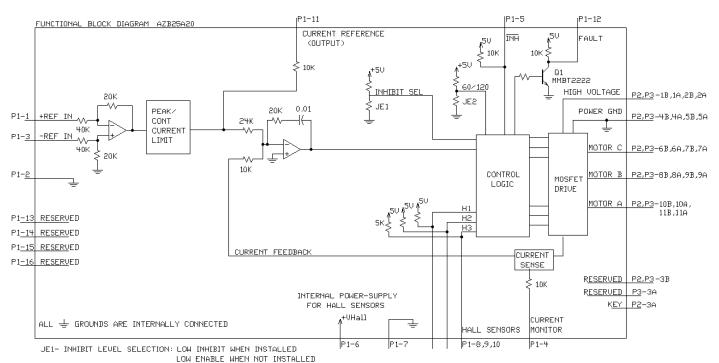
■ ±10 V Analog

#### **COMPLIANCES & AGENCY APPROVALS**

- UI
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS



## **BLOCK DIAGRAM**



JE2- PHASING: 120 DEGREE WHEN INSTALLED, 60 DEGREE WHEN NOT INSTALLED

# US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products. Compliant with European EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 for Emissions, Class A and EN 61000-6-2:2005 for Immunity, Performance Criteria A). LVD requirements of Directive 2006/95/EC (specifically, EN 60204-1:2004, a Low Voltage Directive to protect users from electrical shock). RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.



## **SPECIFICATIONS**

Description	Units VDC VDC	Value	
		10 175	
Supply Voltage Range	VDC	40 – 175	
Bus Under Voltage Limit	VDC	36	
Bus Over Voltage Limit	VDC	193	
imum Peak Output Current <sup>1</sup>	Α	25	
imum Continuous Output Current	Α	12.5	
imum Continuous Output Power	W	2078	
imum Power Dissipation at Continuous Current	W	110	
mum Load Inductance (Line-To-Line) <sup>2</sup>	μН	250	
rnal Bus Capacitance <sup>3</sup>	μF	30	
Voltage Supply Outputs	-	+6 VDC (30 mA)	
ching Frequency	kHz	20.7	
Control Specifications			
Description	Units	Value	
nmand Sources	-	±10 V Analog	
dback Supported	-	Halls	
mutation Methods	-	Trapezoidal	
es of Operation	-	Current	
ors Supported	-	Three Phase (Brushless), Single Phase (Brushed, Voice Coil, Inductive Load)	
dware Protection	-	Invalid Commutation Feedback, Over Current, Over Temperature, Over Voltage, Under Voltage, Short Circuit (Phase-Phase & Phase-Ground)	
Me	chanical	Specifications	
Description	Units	Value	
ncy Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL	
(H x W x D)	mm (in) 76.2 x 50.8 x 22.9 (3 x 2 x 0.9)		
ght	g (oz)	119.7 (4.2)	
: (Base) Temperature Range <sup>4</sup> °C (°F) 0 - 75 (32 - 167)			
age Temperature Range	°C (°F)	-40 - 85 (-40 - 185)	
Connector	-	16-pin, 2.54 mm spaced header	
Connector	-	22-pin, 2.54 mm spaced, dual-row header	

#### Notes

P3 Connector

1. Maximum duration of peak current is ~2 seconds. Peak RMS value must not exceed continuous current rating of the drive.

22-pin, 2.54 mm spaced, dual-row header

- 2. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
- 3. Requires a  $100\mu F/200V$  electrolytic capacitor near the P2 Power Connector between High Voltage and Power Ground pins.
- 4. Additional cooling and/or heatsink may be required to achieve rated performance.



## **PIN FUNCTIONS**

P1 - Signal Connector			
Pin	Name	Description / Notes	1/0
1	+REF IN	Differential Reference Input (±10 V Operating Range, ±15 V Maximum Input)	I
2	SIGNAL GND	Signal Ground	GND
3	-REF IN	Differential Reference Input (±10 V Operating Range, ±15 V Maximum Input)	I
4	CURRENT MONITOR	Current Monitor. Analog output signal proportional to the actual current output. Scaling is 8.3 A/V. Measure relative to signal ground.	0
5	INHIBIT IN	TTL level (+5 V) inhibit/enable input. Leave open to enable drive. Pull to ground to inhibit drive. Inhibit turns off all power devices.	I
6	+V HALL OUT	Low Power Supply For Hall Sensors (+6 V @ 30 mA). Referenced to signal ground. Short circuit protected.	0
7	SIGNAL GND	Signal Ground	GND
8	HALL 1		I
9	HALL 2*	Single-ended Hall/Commutation Sensor Inputs (+5 V logic level)	
10	HALL 3		
11	CURRENT REFERENCE	Measures the command signal to the internal current-loop. This pin has a maximum output of ±7.3 V when the drive outputs maximum peak current. Measure relative to signal ground.	0
12	FAULT OUT	TTL level (+5 V) output becomes high when power devices are disabled due to at least one of the following conditions: inhibit, invalid Hall state, output short circuit, over voltage, over temperature, power-up reset.	0
13	RESERVED		-
14	RESERVED	Reserved	
15	RESERVED		
16	RESERVED		

	P2 and P3 - Power Connector			
Pi	n	Name	Description / Notes	1/0
1b	1a	HIGH VOLTAGE	DC Power Input. 3A Continuous Current Rating Per Pin. Requires a 100 $\mu$ F / 200 V external	I
2b	2a	HIGH VOLTAGE	<ul> <li>electrolytic capacitor connected as close as possible to pins between High Voltage and Power Ground.</li> </ul>	
3b		NC	Not Connected (Reserved)	-
	3a	NC (KEY)	Key: No Connection (pin removed) for P2. Not Connected (Reserved) for P3.	-
4b	4a	PWR GND	Device Occupat (Occupant Mith Circuit Occupat) 2A Occubious Compant Detical Despite	GND
5b	5a	PWR GND	Power Ground (Common With Signal Ground). 3A Continuous Current Rating Per Pin.	
6b	6a	MOTOR C		0
7b	7a	MOTOR C		
8b	8a	MOTOR B	Motor Phase Outputs. Current output distributed equally across both P2 and P3 connectors	0
9b	9a	MOTOR B	- 8 pins per motor phase, 3A continuous current carrying capacity per pin.	
10b	10a	MOTOR A		
11b	11a	MOTOR A		

<sup>\*</sup>For use with Single Phase (Brushed) motors, ground Hall 2 and only connect motor leads to Motor A and Motor B.

# **HARDWARE SETTINGS**

## **Jumper Settings**

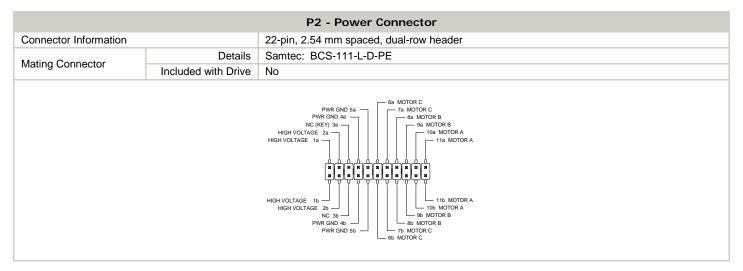
Jumpers are SMT, 0 ohm resistors located on the underside of the drive PCB. By default, the drive is configured with the jumpers installed. Typical drive operation will not require the jumpers to be removed. Please contact the factory before jumper removal.

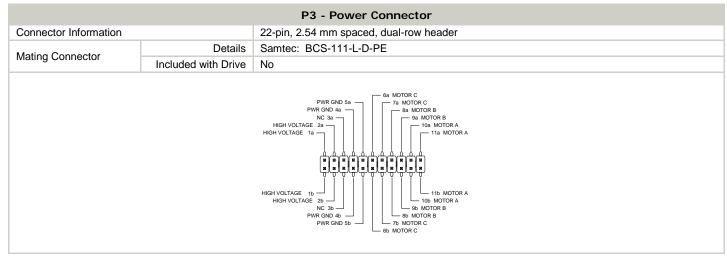
Jump	er Description	Configuration	
	SMT Jumper (0Ω Resistor)	Not Installed	Installed
JE1	Inhibit logic. Sets the logic level of inhibit pins. Labeled JE1 on the PCB of the drive.	Low Enable	Low Inhibit
JE2	Hall sensor phasing. Selects 120 or 60 degree commutation phasing. Labeled JE2 on the PCB of the drive.	60 degree	120 degree



## MECHANICAL INFORMATION

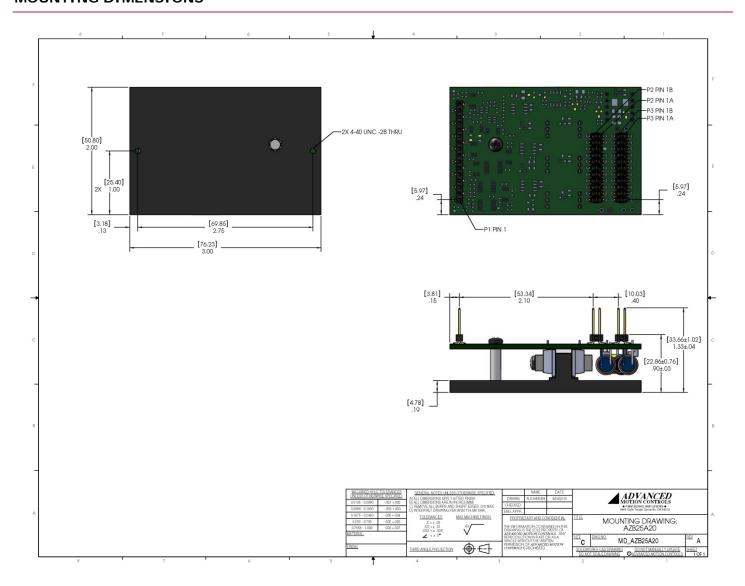
P1 - Signal Connector			
Connector Information	Connector Information 16-pin, 2.54 mm spaced header		
Mating Connector	Details	Samtec: BCS-116-L-S-PE	
	Included with Drive	No	
11 CURRENT REFERENCE  9 HALL 2  7 SIGNAL GND  3 -REF IN  1 +REF IN  2 SIGNAL GND  4 CURRENT MONITOR  8 HALL 1  10 HALL 3  12 FAULT OUT			





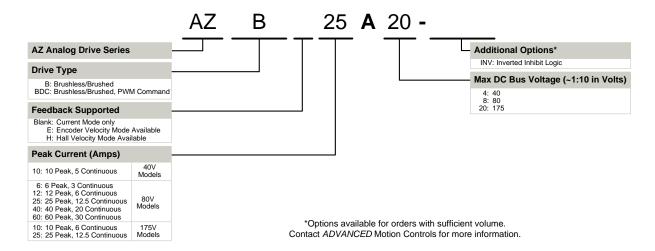


# MOUNTING DIMENSIONS





#### PART NUMBERING INFORMATION



ADVANCED Motion Controls AZ series of servo drives are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

# **Examples of Modifications and Customized Products**

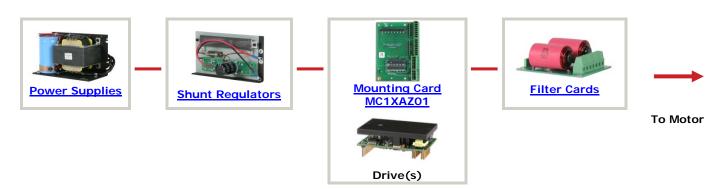
- ▲ Integration of Drive into Motor Housing
- ▲ Mount OEM PCB onto Drive Without Cables
- Multi-axis Configuration for Compact System
- ▲ Custom PCB and Baseplate for Optimized Footprint
- ▲ RTV/Epoxy Components for High Vibration
- OEM Specified Connectors for Instant Compatibility
- ▲ OEM Specified Silkscreen for Custom Appearance
- ▲ Increased Thermal Limits for High Temp. Operation
- ▲ Integrate OEM Circuitry onto Drive PCB
- Custom Control Loop Tuned to Motor Characteristics

- Optimized Switching Frequency
- ▲ Ramped Velocity Command for Smooth Acceleration
- ▲ Remove Unused Features to Reduce OEM Cost
- ▲ Application Specific Current and Voltage Limits

Feel free to contact Applications Engineering for further information and details.

# **Available Accessories**

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit <a href="https://www.a-m-c.com">www.a-m-c.com</a> to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.