

Description

The AZB10A4 PWM servo drive is designed to drive brushless and brushed DC motors at a high switching frequency. To increase system reliability and to reduce cabling costs, the drive is designed for direct integration into your PCB. The AZB10A4 is fully protected against over-voltage, under-voltage, over-current, over-heating, and short-circuits. A single digital output indicates operating status. The drive interfaces with digital controllers that have analog ±10V output. This servo drive requires only a single unregulated isolated DC power supply, and is fully RoHS (Reduction of Hazardous Substances) compliant.

See Part Numbering Information on last page of datasheet for additional ordering options.

Power Range	
Peak Current	10 A
Continuous Current	5 A
Supply Voltage	10 - 36 VDC



Features

- ▲ Four Quadrant Regenerative Operation
- Direct Board-to-Board Integration
- Lightweight
- High Switching Frequency
- Differential Input Command

- Digital Fault Output Monitor
- ▲ Current Monitor Output
- ▲ Single Supply Operation
- Compact Size
- ▲ High Power Density
- 12VDC Operation

HARDWARE PROTECTION

- Over-Voltage
- Under-Voltage
- Over-Current
- Over-Temperature
- Short-circuit (phase-phase)
- Short-circuit (phase-ground)

INPUTS/OUTPUTS

- Digital Fault Output
- Digital Inhibit Input
- Analog Current Monitor
- Analog Command Input

FEEDBACK SUPPORTED

Hall Sensors

MODES OF OPERATION

Current

COMMUTATION

Trapezoidal

MOTORS SUPPORTED

- Three Phase (Brushless)
- Single Phase (Brushed, Voice Coil, Inductive Load)

COMMAND SOURCE

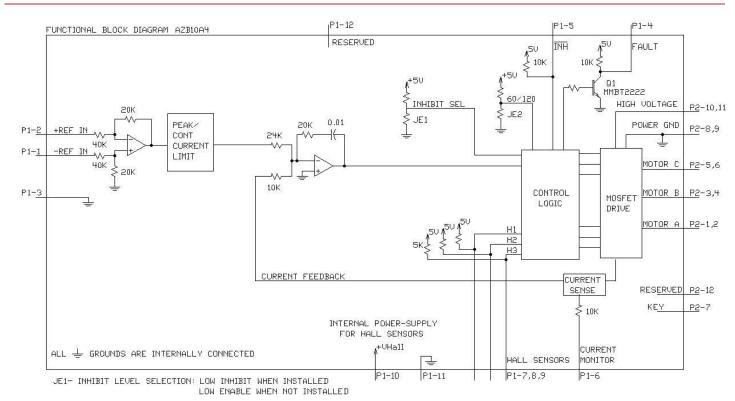
■ ±10 V Analog

COMPLIANCES & AGENCY APPROVALS

- RoHS
- UL/cUL Pending
- CE Pending



BLOCK DIAGRAM



JE2- PHASING: 120 DEGREE WHEN INSTALLED, 60 DEGREE WHEN NOT INSTALLED

Information on Approvals and Compliances



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.



SPECIFICATIONS

Power Specifications			
Description	Units	Value	
DC Supply Voltage Range	VDC	10 - 36	
DC Bus Under Voltage Limit	VDC	8	
DC Bus Over Voltage Limit	VDC	40	
Maximum Peak Output Current ¹	A	10	
Maximum Continuous Output Current	A	5	
Maximum Continuous Output Power	W	171	
Maximum Power Dissipation at Continuous Current	W	9	
Minimum Load Inductance (Line-To-Line) ²	μН	100	
Internal Bus Capacitance ³	μF	23.5	
Low Voltage Supply Outputs	-	+5 VDC (30 mA)	
Switching Frequency	kHz	40	
Control Specifications			
Description	Units	Value	
Command Sources	-	±10 V Analog	
Feedback Supported	-	Halls	
Commutation Methods	-	Trapezoidal	
Modes of Operation	-	Current	
Motors Supported	-	Three Phase (Brushless), Single Phase (Brushed, Voice Coil, Inductive Load)	
Hardware Protection	-	Invalid Commutation Feedback, Over Current, Over Temperature, Over Voltage, Under Voltage, Short Circuit (Phase-Phase & Phase-Ground)	
	Mechanical Specifications		
Description	Description Units Value		
Agency Approvals	-	RoHS, UL/cUL Pending, CE Pending	
Size (H x W x D)	mm (in)	38.1 x 38.1 x 7.34 (1.50 x 1.50 x 0.29)	
Weight	g (oz)	8.5 (0.3)	
Operating Temperature Range ⁴	°C (°F)	0 - 85 (32 - 185)	
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)	
Relative Humidity	-	0 - 90% Non-Condensing	

Notes

Form Factor P1 Connector

P2 Connector

Maximum duration of peak current is ~2 seconds. Peak RMS value must not exceed continuous current rating of the drive.

PCB Mounted

12-pin, 1.27 mm spaced header

12-pin, 1.27 mm spaced header

- 2. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
- Requires a minimum of 47 μ F external bus capacitance between the DC Supply and Power Ground. Additional cooling and/or heatsink may be required to achieve rated performance. 3.



PIN FUNCTIONS

		P1 - Signal Connector	
Pin	Name	Description / Notes	1/0
1	-REF IN	Differential Reference Input (±10 V Operating Range, ±15 V Maximum Input)	I
2	+REF IN	Differential Reference Input (±10 V Operating Range, ±15 V Maximum Input)	I
3	SIGNAL GND	Signal Ground (Common With Power Ground).	GND
4	FAULT OUT	TTL level (+5 V) output becomes high when power devices are disabled due to at least one of the following conditions: inhibit, invalid Hall state, output short circuit, over voltage, over temperature, power-up reset.	0
5	INHIBIT IN	TTL level (+5 V) inhibit/enable input. Leave open to enable drive. Pull to ground to inhibit drive. Inhibit turns off all power devices.	I
6	CURRENT MONITOR	Current Monitor. Analog output signal proportional to the actual current output. Scaling is 2 A/V. Measure relative to signal ground.	0
7	HALL 3		I
8	HALL 2*	Single-ended Hall/Commutation Sensor Inputs (+5 V logic level)	
9	HALL 1		
10	+V HALL OUT	Low Power Supply For Hall Sensors (+5 V @ 30 mA). Referenced to signal ground. Short circuit protected.	0
11	SIGNAL GND	Signal Ground (Common With Power Ground).	GND
12	RESERVED	Reserved	-

P2 - Power Connector			
Pin	Name	Description / Notes	1/0
1	MOTOR A	- ·	
2	MOTOR A		
3	MOTOR B	Motor Phase Outputs. Current output distributed equally across 2 pins per motor phase, 3A	0
4	MOTOR B	continuous current carrying capacity per pin.	
5	MOTOR C		
6	MOTOR C		
7	NC (KEY)	No Connection. Keyed pin.	-
8	PWR GND	Dower Crowned (Common With Cignal Crowned) 2A Continuous Current Dating Day Din	GND
9	PWR GND	Power Ground (Common With Signal Ground). 3A Continuous Current Rating Per Pin	
10	HV IN	DC Power Input. 3A Continuous Current Rating Per Pin. Requires a minimum of 47 μF external capacitance between HV IN and PWR GND pins.	
11	HV IN		
12	RESERVED	Reserved	-

^{*}For use with Single Phase (Brushed) motors, ground Hall 2 and only connect motor leads to Motor A and Motor B.

Note: P1 and P2 are identical 12-pin headers. To avoid damage to the drive, be sure when plugging or soldering the drive into a PCB or interface card that the drive orientation is correct. P1 and P2 are labeled on the PCB silkscreen. Pin 7 on P2 is keyed to differentiate it from P1. Consult the mounting dimension drawing on page 6 of this datasheet for an illustration of the locations of P1 and P2.

HARDWARE SETTINGS

Jumper Settings

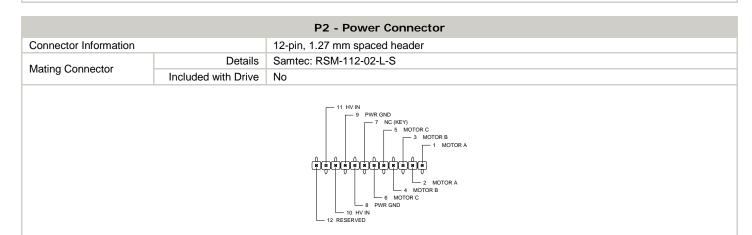
Jumpers are SMT, 0 ohm resistors located on the underside of the drive PCB. By default, the drive is configured with the jumpers installed. Typical drive operation will not require the jumpers to be removed. Please contact the factory before jumper removal.

Jumper	Jumper Description		Configuration	
	SMT Jumper (0Ω Resistor)	Not Installed	Installed	
JE1	Inhibit logic. Sets the logic level of inhibit pins. Labeled JE1 on the PCB of the drive.	Low Enable	Low Inhibit	
JE2	Hall sensor phasing. Selects 120 or 60 degree commutation phasing. Labeled JE2 on the PCB of the drive.	60 degree	120 degree	



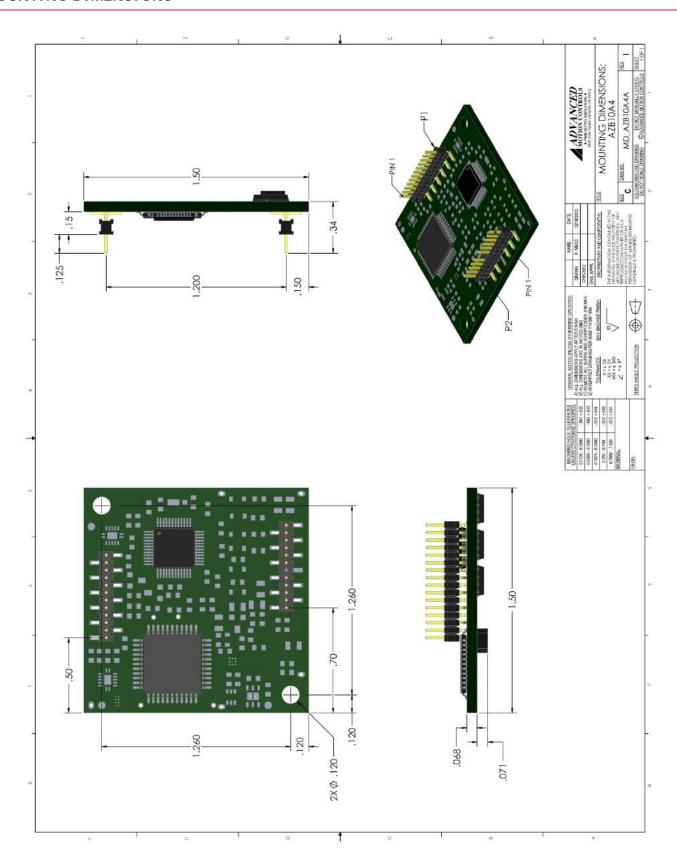
MECHANICAL INFORMATION

P1 - Signal Connector			
Connector Information		12-pin, 1.27 mm spaced header	
Details		Samtec: RSM-112-02-L-S	
Mating Connector	Included with Drive	No	
		11 SIGNAL GND 9 HALL 1 7 HALL 3 1 -REF IN 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	



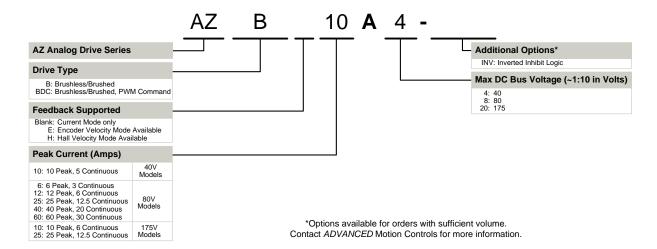


MOUNTING DIMENSIONS





PART NUMBERING INFORMATION



ADVANCED Motion Controls AZ series of servo drives are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

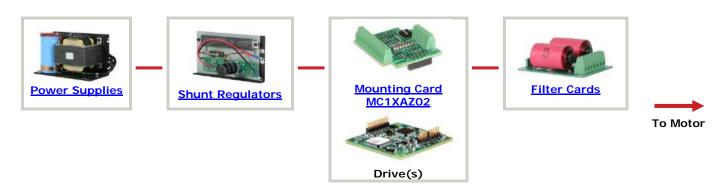
Examples of Modifications and Customized Products

- ▲ Integration of Drive into Motor Housing
- ▲ Mount OEM PCB onto Drive Without Cables
- ▲ Multi-axis Configuration for Compact System
- Custom PCB and Baseplate for Optimized Footprint
- ▲ RTV/Epoxy Components for High Vibration
- OEM Specified Connectors for Instant Compatibility
- ▲ OEM Specified Silkscreen for Custom Appearance
- ▲ Increased Thermal Limits for High Temp. Operation
- ▲ Integrate OEM Circuitry onto Drive PCB
- Custom Control Loop Tuned to Motor Characteristics
- ▲ Custom I/O Interface for System Compatibility
- ▲ Preset Switches and Pots to Reduce User Setup
- Optimized Switching Frequency
- ▲ Ramped Velocity Command for Smooth Acceleration
- ▲ Remove Unused Features to Reduce OEM Cost
- Application Specific Current and Voltage Limits

Feel free to contact Applications Engineering for further information and details.

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.