

**Description**

The S16A8 PWM servo drive is designed to drive three phase brushless motors with sine wave current at a high switching frequency. The drive requires two sinusoidal command signals with a 120-degree phase shift (external commutation). The phase angle must correspond to the position of the motor rotor, while the signal amplitude controls the motor torque. The S16A8 interfaces directly with digital controllers. The drive is fully protected against over-voltage, over-current, over-heating, and short-circuits, and requires only a single unregulated DC power supply (all logic and control voltages are generated internally). A red/green LED and two digital outputs indicate operating status.

See Part Numbering Information on last page of datasheet for additional ordering options. The hardware installation manual for the analog drive family is available for download at [www.a-m-c.com](http://www.a-m-c.com).

**Power Range**

Peak Current	16 A (11.3 A <sub>RMS</sub> )
Continuous Current	8 A <sub>RMS</sub>
Supply Voltage	20 - 80 VDC



**Features**

- ▲ Four Quadrant Regenerative Operation
- ▲ Adjustable Current Limits
- ▲ High Switching Frequency
- ▲ Differential Input Command
- ▲ Selectable Inhibit/Enable Logic
- ▲ Digital Fault Output Monitor
- ▲ Sinusoidal Current Output
- ▲ Adjustable Input Gain
- ▲ DIP Switch Selectable Tuning
- ▲ Drive Status LED
- ▲ Current Monitor Output
- ▲ No Crossover Distortion

**MODES OF OPERATION**

- Current

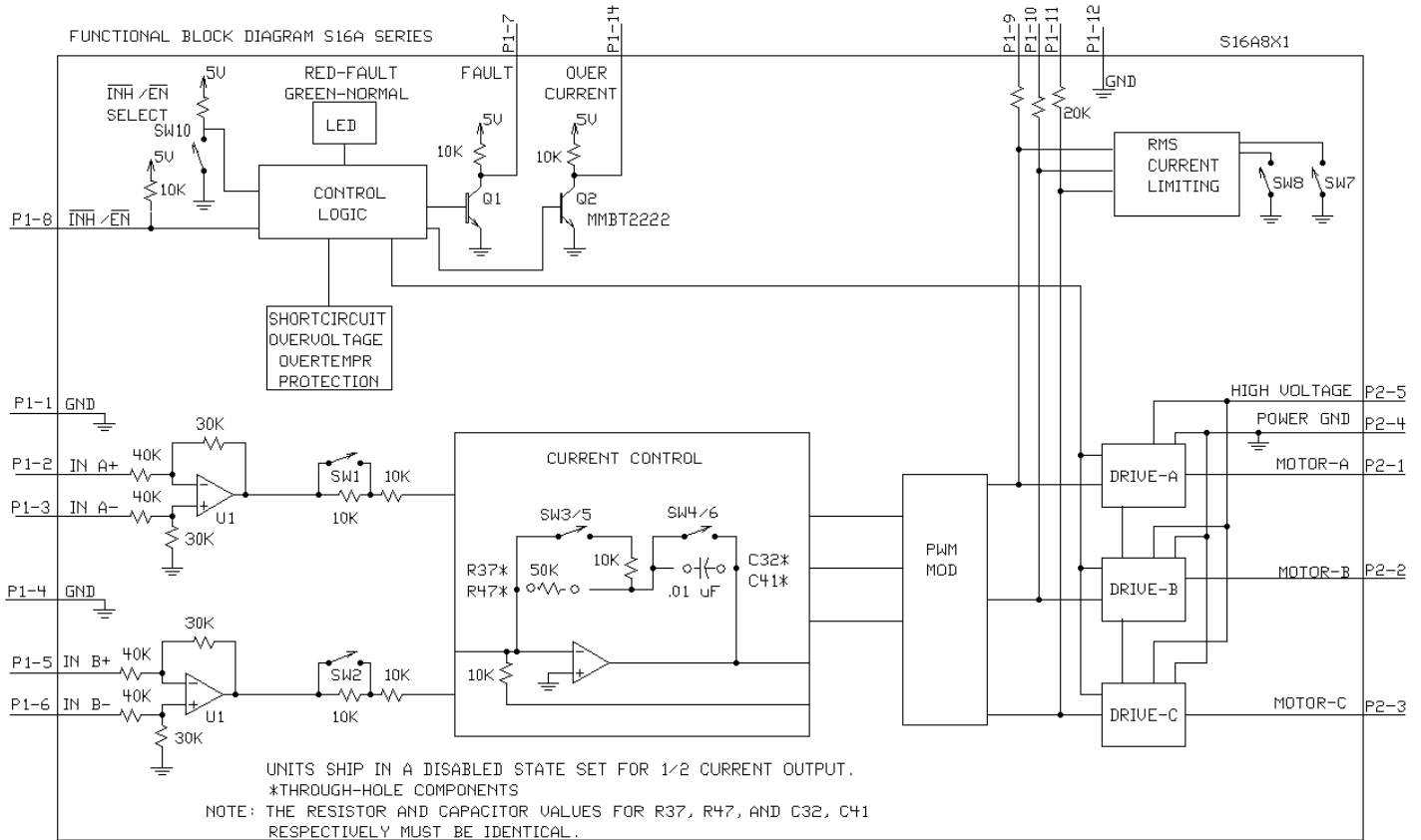
**COMMAND SOURCE**

- 120° Sine




**COMPLIANCES & AGENCY APPROVALS**

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS

**BLOCK DIAGRAM**



**Information on Approvals and Compliances**

	<p>US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.</p>
	<p>Compliant with European EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 for Emissions, Class A and EN 61000-6-2:2005 for Immunity, Performance Criteria A). LVD requirements of Directive 2006/95/EC (specifically, EN 60204-1:2004, a Low Voltage Directive to protect users from electrical shock).</p>
	<p>RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.</p>

**SPECIFICATIONS**

Power Specifications		
Description	Units	Value
DC Supply Voltage Range	VDC	20 - 80
DC Bus Over Voltage Limit	VDC	86
Maximum Peak Output Current <sup>1</sup>	A	16
Maximum Continuous Sine Wave Current	Arms	8
Maximum Continuous Output Power	W	608
Maximum Power Dissipation at Continuous Current	W	32
Minimum Load Inductance (Line-To-Line) <sup>2</sup>	μH	200
Switching Frequency	kHz	33
Control Specifications		
Description	Units	Value
Command Sources	-	120° Sine
Commutation Methods	-	Sinusoidal
Modes of Operation	-	Current
Motors Supported	-	Three Phase (Brushless)
Hardware Protection	-	Over Current, Over Temperature, Over Voltage, Short Circuit (Phase-Phase & Phase-Ground)
Primary I/O Logic Level	-	5V TTL
Mechanical Specifications		
Description	Units	Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL
Size (H x W x D)	mm (in)	129.3 x 77.7 x 38.6 (5.1 x 3.1 x 1.5)
Weight	g (oz)	280 (9.9)
Heatsink (Base) Temperature Range <sup>3</sup>	°C (°F)	0 - 65 (32 - 149)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Form Factor	-	Panel Mount
P1 Connector	-	15-pin, female D-sub
P2 Connector	-	5-port, 5.08 mm spaced, screw terminal

**Notes**

1. Maximum duration of peak current is ~2 seconds.
2. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
3. Additional cooling and/or heatsink may be required to achieve rated performance.

**PIN FUNCTIONS**

P1 - Signal Connector			
Pin	Name	Description / Notes	I/O
1	SIGNAL GND	Signal Ground	GND
2	+REF-IN-A	Differential reference input, maximum $\pm 10$ V, 40K input resistance	I
3	-REF-IN-A		I
4	SIGNAL GND	Signal Ground	GND
5	+REF-IN-B	Differential reference input, maximum $\pm 10$ V, 40K input resistance	I
6	-REF-IN-B		I
7	FAULT OUT	TTL level (+5 V) output becomes high when power devices are disabled due to at least one of the following conditions: inhibit, output short circuit, over voltage, over temperature, power-up reset.	O
8	INHIBIT/ENABLE IN	TTL level (+5 V) inhibit/enable input. Pull to ground to enable drive (SW10-ON). Pull to ground to inhibit drive (SW10-OFF). Inhibit turns off all power devices.	I
9	CURR. MON. A OUT	Phase Current Monitor. 7.25 V = amplifier peak rated current .	O
10	CURR. MON. B OUT		O
11	CURR. MON. C OUT		O
12	SIGNAL GND	Signal Ground	GND
13	NC	Not Connected (Reserved)	-
14	OVER CURR. OUT	This transistor output becomes high if RMS current (in any phase) exceeds RMS current limit. This creates a fault condition. Drive will re-enable when the RMS current returns to values within the RMS current limit range.	O
15	NC	Not Connected (Reserved)	-

P2 - Power Connector			
Pin	Name	Description / Notes	I/O
1	MOTOR A	Motor Phase A	O
2	MOTOR B	Motor Phase B	O
3	MOTOR C	Motor Phase C	O
4	POWER GND	Power Ground (Common With Signal Ground)	GND
5	HIGH VOLTAGE	DC Power Input	I

## HARDWARE SETTINGS

### Switch Functions

Switch	Description	Setting	
		On	Off
1	Peak Current Limit. Sets the peak current limit to 50% or 100% of the maximum peak current. Must be set the same as switch 2.	100%	50%
2	Peak Current Limit. Sets the peak current limit to 50% or 100% of the maximum peak current. Must be set the same as switch 1.	100%	50%
3	Current loop proportional gain adjustment. Must be set the same as switch 5. ON by default.	Decrease	Increase
4	Current loop integral gain. Activates or deactivates integration. Must be set the same as switch 6. OFF by default.	Inactive	Active
5	Current loop proportional gain adjustment. Must be set the same as switch 3. ON by default.	Decrease	Increase
6	Current loop integral gain. Activates or deactivates integration. Must be set the same as switch 4. OFF by default.	Inactive	Active
7	Bit 0 of binary value for RMS current limit setting. See details below.	1	0
8	Bit 1 of binary value for RMS current limit setting. See details below.	1	0
9	Reserved Function	-	-
10	Inhibit logic. Sets the logic level of inhibit pins.	Active High	Active Low

#### Additional Details

Switches 1 & 2, switches 3 & 5, and switches 4 & 6 must be set the same. Switches 7 and 8 can be used to reduce the continuous current limit to a percentage given in the table below. 100% means no reduction.

% Of Maximum Continuous Current Limit	Switch 7	Switch 8
25	OFF	OFF
50	OFF	ON
100	ON	OFF
	ON	ON

### Through-hole Components<sup>†</sup>

Location	Description
C32*	Current Loop Integrator. Two identical through-hole capacitors that can be added for more precise current loop tuning. See section below on Tuning with Through-hole components for more details.
C41*	
R37*	Current Loop Proportional Gain. Two identical through-hole resistors that can be added for more precise current loop tuning. See section below on Tuning with Through-hole components for more details.
R47*	

#### Tuning With Through-hole Components

In general, the drive will not need to be further tuned with through-hole components. However, for applications requiring more precise tuning than what is offered by the potentiometers and dipswitches, the drive can be manually modified with through-hole resistors and capacitors as denoted in the above table. By default, the through-hole locations are not populated when the drive is shipped. Before attempting to add through-hole components to the board, consult the section on loop tuning in the installation notes on the manufacturer's website. Some general rules of thumb to follow when adding through-hole components are:

- A larger resistor value will increase the proportional gain, and therefore create a faster response time.
- A larger capacitor value will increase the integration time, and therefore create a slower response time.

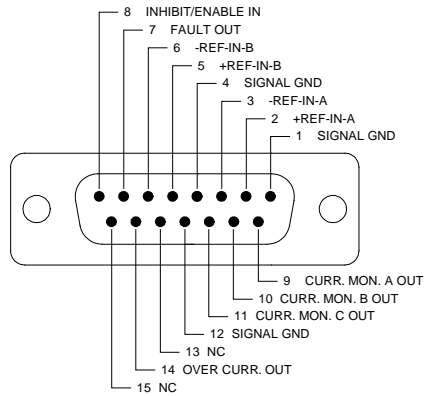
Proper tuning using the through-hole components will require careful observation of the loop response on a digital oscilloscope to find the optimal through-hole component values for the specific application.

<sup>†</sup>**Note: Damage done to the drive while performing these modifications will void the warranty.**

**MECHANICAL INFORMATION**

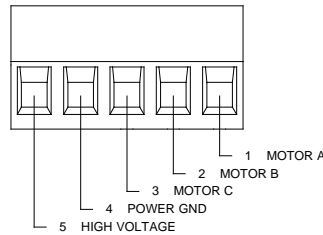
**P1 - Signal Connector**

Connector Information		15-pin, female D-sub
Mating Connector	Details	TYCO: Plug P/N 205206-3; Housing P/N 5745172-1; Terminals P/N 1658540-5 (loose) or 1658540-4 (strip)
	Included with Drive	No

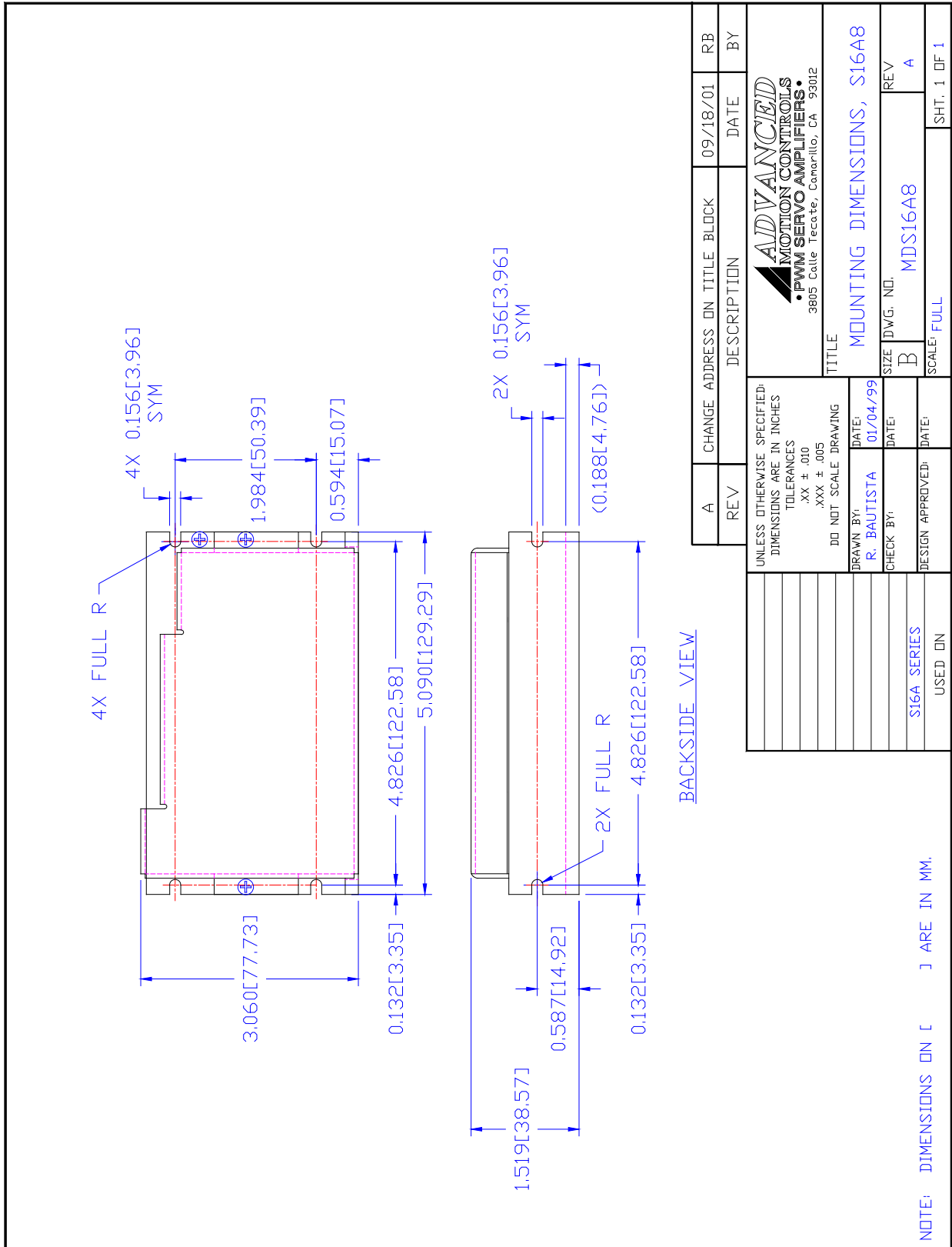


**P2 - Power Connector**

Connector Information		5-port, 5.08 mm spaced, screw terminal
Mating Connector	Details	Not applicable
	Included with Drive	Not applicable

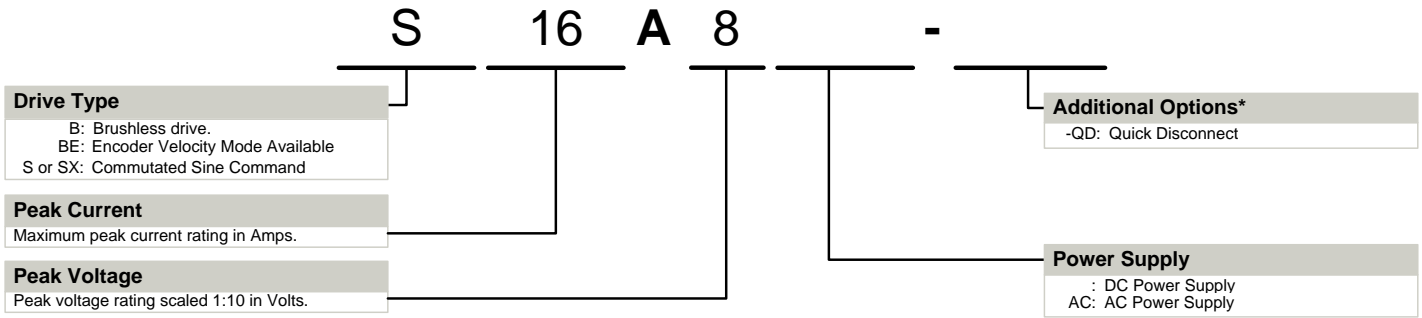


**MOUNTING DIMENSIONS**



A	CHANGE ADDRESS ON	TITLE	BLOCK	09/18/01	DATE	RB
REV	DESCRIPTION					
		 <b>ADVANCED MOTION CONTROLS</b> • PWM SERVO AMPLIFIERS • 3805 Calle Tecate, Camarillo, CA 93012				
		TITLE				
		MOUNTING DIMENSIONS, S16A8				
		SIZE	DWG. NO.	REV		
		B	MDS16A8	A		
		SCALE:	FULL	SHT.	1	DF 1
		DRAWN BY:	R. BAUTISTA	DATE:	01/04/99	
		CHECK BY:		DATE:		
		DESIGN APPROVED:		DATE:		
		S16A SERIES USED ON				

**PART NUMBERING INFORMATION**



\* Options available for orders with sufficient volume. Contact *ADVANCED* Motion Controls for more information.

*ADVANCED* Motion Controls analog series of servo drives are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

*ADVANCED* Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, *ADVANCED* Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

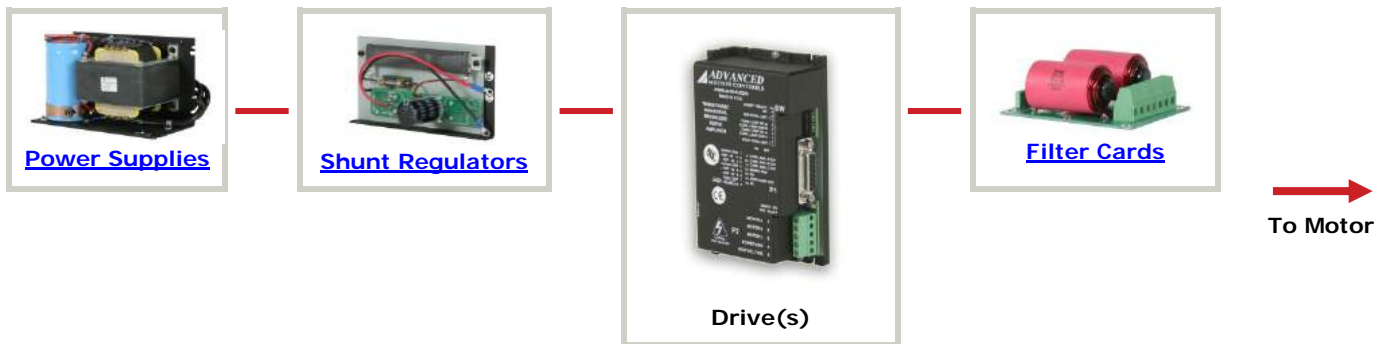
**Examples of Modifications and Customized Products**

- ▲ Integration of Drive into Motor Housing
- ▲ Mount OEM PCB onto Drive Without Cables
- ▲ Multi-axis Configuration for Compact System
- ▲ Custom PCB and Baseplate for Optimized Footprint
- ▲ RTV/Epoxy Components for High Vibration
- ▲ OEM Specified Connectors for Instant Compatibility
- ▲ OEM Specified Silkscreen for Custom Appearance
- ▲ Increased Thermal Limits for High Temp. Operation
- ▲ Integrate OEM Circuitry onto Drive PCB
- ▲ Custom Control Loop Tuned to Motor Characteristics
- ▲ Custom I/O Interface for System Compatibility
- ▲ Preset Switches and Pots to Reduce User Setup
- ▲ Optimized Switching Frequency
- ▲ Ramped Velocity Command for Smooth Acceleration
- ▲ Remove Unused Features to Reduce OEM Cost
- ▲ Application Specific Current and Voltage Limits

Feel free to contact Applications Engineering for further information and details.

**Available Accessories**

*ADVANCED* Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit [www.a-m-c.com](http://www.a-m-c.com) to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.